

# Set-Based Comprehensive Learning Particle Swarm Optimization for Virtual Machine Placement Problem

Yue Weng, Wei-Neng Chen, An Song, and Jun Zhang  
School of Computer Science and Engineering,  
Provincial Key Lab of Computational Intelligence and Cyberspace Information,  
South China University of Technology,  
Guangzhou, China  
Email: cwnraul634@aliyun.com

**Abstract**—The virtual machine placement (VMP) is a significant technology in energy-saving field, which is an increasingly important problem of cloud computing centers. Most existing algorithms are difficult to handle the large-scale VMP problems with heterogeneous resources and large demand of virtual machines. In this paper, we propose the set-based comprehensive learning particle swarm optimization (SCLPSO) to solve the VMP problem. SCLPSO combines the set-based particle swarm optimization framework (S-PSO) with the comprehensive learning particle swarm optimizer. With the S-PSO framework, SCLPSO is able to solve the VMP problem which is defined on the discrete search space. With the redefined velocity updating rule in SCLPSO, each dimension of a particle can potentially learn from different exemplars. This strategy improves the exploration of the algorithm. The algorithm also introduces a heuristic factor to guide a virtual machine (VM) to be placed on a more suitable physical machine (PM), which improves the resource utilization of the PM. Based on the devised strategies, large-scale VMP problems with heterogeneous resources can be well resolved by SCLPSO. We conduct experiments on different instances and compare SCLPSO with other classical algorithms. The experimental results demonstrate that the proposed algorithm is promising.

**Keywords**—Cloud computing, virtual machine placement (VMP), set-based comprehensive learning particle swarm optimization (SCLPSO), particle swarm optimization (PSO).

## I. INTRODUCTION

The emergence of cloud computing satisfies people's increasing demand for computing resources. With virtualization technology, users can purchase various physical resources they need (e.g., CPU and memory) and need not care about the distribution and configuration of physical machine (PM). Cloud computing centers provide users with three types of services: Infrastructure as a Service (IaaS), Platform as a Service (PaaS) and Software as a Service (SaaS) [1]. A virtual machine (VM) can be assigned to a physical machine in the cloud computing center according to users' requirements of resources.

With the expanding of cloud computing centers, the number of physical machines continues to increase, and the amount of consumed energy to power and cool physical machines is also increasing. Nearly half of the power consumption in cloud computing centers is used for the cooling of physical machines [2]. Even idle physical machines consume up to 66% of the peak power to maintain operating devices and other hardware resources [3]. Therefore, the key to solve the energy consumption problem is to reduce the number of active physical

machines as much as possible and shut down idle physical machines.

Virtualization technology allows multiple virtual machines to be distributed on the same physical machine to share physical resources without affecting each other, which is called the virtual machine placement (VMP) problem. How to map all virtual machines to suitable physical machines is a NP-hard problem [4]. The solution space grows exponentially as the scale of the problem increases, making the enumeration impossible.

As the VMP problem is challenging, considerable amount of research efforts has been devoted to VMP. From the perspective of problem model, Aggarwal *et al.* [5] studied the important layout goals and constraints of VMP problem, and designed heuristics algorithms. As for disk placement, Hbaieb *et al.* [6] proposed a decomposition and local search method. Xia *et al.* [7] proposed a hierarchical decomposition and mixed integer programming (MIP) approach to solve the problem that restricts the VM virtual disk from being distributed over the PM physical disk. While some scholars proposed virtual machine migration technology to achieve server consolidation and minimize the use of low-utility servers [8]-[11]. During the placement process, the position of VM will be migrated to another PM for better assignment. On the other hand, from the perspective of the algorithm, Alboaneen *et al.* [12] introduced metaheuristic methods for VMP, including individual-based algorithms like simulated annealing (SA), reproductive population-based algorithms like genetic algorithm (GA), and non-reproductive population-based algorithms like biogeography-based optimization (BBO). Ajiro *et al.* [13] proposed another heuristic algorithm called First-Fit Decreasing (FFD) to solve VMP. Through these heuristics, a feasible solution can be found in a short time using the greedy search method. But as the problem scale increases, the quality of the solutions found by simple heuristics degenerates. As for meta-heuristics, Gao *et al.* [14] proposed a solution based on the ant colony algorithm to solve VMP problem, which is able to generate more promising solutions. Based on GA, Jamali *et al.* [15] proposed an improved grouping-based genetic algorithm (IGGA) to minimize the number of physical machines and maximize the utilization of resources as well.

In order to develop a more effective approach to VMP, this paper puts forward the SCLPSO algorithm combining both set-based discrete particle swarm optimization framework (S-PSO) [16] and the velocity updating rule in comprehensive learning PSO (CLPSO) [17]. We also pay attention to the allocation and

utilization of both CPU and memory resources. The main contribution of this work can be summarized as follows:

1) SCLPSO combines both the S-PSO framework and the velocity updating strategy of CLPSO. S-PSO framework extends the original PSO to discrete space, so that we can use PSO to solve discretization problems. Comprehensive learning strategy maintains a good searching diversity so that the proposed approach can achieve good performance on the considered problem.

2) In order to measure the connection of the VM and PM, we design the heuristic which can improve the utilization of different resources and provide a better assignment.

The remainder of the paper is organized as follows. Section II will introduce the background of the PSO, S-PSO and CLPSO. Section III will formulate the VMP problem. Section IV will introduce the proposed SCLPSO algorithm. Experimental studies on large-scale problems in both homogeneous and heterogeneous environments are presented in Section V. Conclusion is drawn in Section VI.

## II. BACKGROUND

### A. The Original PSO

Particle swarm optimization (PSO) was proposed by Kennedy and Eberhart in 1995 [18]-[22]. It is a population-based heuristic algorithm and is often used to solve problems in continuous space. PSO sets  $M$  particles to find the globally optimal solution in a  $n$ -dimensional continuous space. The algorithm initializes a population of swarm randomly at the beginning and evaluates their fitness values. Then it uses (1) and (2) to update the position and velocity of each particle, where  $v_i^d$  is the  $d$ -th dimension of the velocity of the  $i$ -th particle, and  $x_i^d$  is the  $d$ -th dimension of the position of the  $i$ -th particle. With the guidance from the personal historically best position ( $pbest$ ) and the globally historically best position ( $gbest$ ) of the whole swarm, particles update their positions iteratively to seek for the optimal solution in the search space.

$$v_i^d = wv_i^d + c_1r_1(pbest_i^d - x_i^d) + c_2r_2(gbest^d - x_i^d), \quad (1)$$

$$x_i^d = x_i^d + v_i^d. \quad (2)$$

### B. The Set-Based PSO Framework

The original PSO cannot be used in discrete space directly because both (1) and (2) are defined in continuous space. To solve this problem, Chen *et al.* [16] proposed a novel set-based particle swarm optimization (S-PSO) method for discrete optimization problems [23]. S-PSO [24], [25] adopts the concept of crisp set and redefines the representation of "position" and "velocity" as well as other related operations, so that the updating rules (1) and (2) can be applied to solve discretization problems. The framework can be well applied to other PSO variants [16]. In S-PSO, the position of particle  $i$  is defined as a crisp set  $X_i$  and the velocity of particle  $i$  is defined as a set of probabilities  $V_i$ , as shown in (3). The element in each velocity set is associated with a probability  $p(e)$ .  $p(e)$  is the probability that determines whether particle  $i$  will learn from the element  $e$  to build a new position.

$$V_i = \{e / p(e) | e \in E\}. \quad (3)$$

### C. CLPSO

In order to enhance the searching diversity of PSO, Liang *et al.* [17] proposed a comprehensive learning PSO employing a novel learning strategy to update the velocity. Any particle can learn from other particles' previous best positions and each dimension of a particle can potentially learn from a different exemplar. The updating strategy is defined as follows:

$$V_i^d = \omega * V_i^d + c * rand_i^d * (pbest_{fi(d)}^d - X_i^d), \quad (4)$$

where  $c$  is a parameter,  $rand_i^d$  is a random number in  $[0,1]$ , and  $pbest_{fi(d)}^d$  is the  $d$ -th dimension of the  $pbest$  position of particle  $fi(d)$ .  $fi(d)$  is given as follows. First, a random number  $ran \in [0,1]$  is generated. If  $ran$  is larger than a parameter  $Pc$ , then  $fi(d) = i$ . Otherwise, the algorithm applies the tournament selection on two randomly selected particles. The particle with better fitness will be selected. We do this process in each dimension for each particle, so that each particle and each dimension can learn from different particles. The parameter  $Pc$  for the  $i$ -th particle is defined as follows:

$$Pc_i = 0.05 + 0.45 * \frac{\left( \exp\left(\frac{10(i-1)}{POPSIZE-1}\right) - 1 \right)}{(\exp(10) - 1)}. \quad (5)$$

CLPSO has shown excellent performance for complex multimodal optimization problems [17]. Therefore, in this paper, we combine this updating strategy and the S-PSO framework together to improve the performance of PSO in solving VMP.

## III. PROBLEM DEFINITION

Virtualization technology is the core part of cloud computing. The cloud computing center receives user's requests and creates a virtual machine that meets user's requirements, including a specific number of CPUs, memory, hard disks, etc. Then the cloud computing center assigns VMs to PMs that have enough remaining physical resources. A reasonable allocation scheme can reduce the number of active physical machines, and thus can save energy consumption of cloud computing centers.

The purpose of the VMP problem is to find an optimal VM allocation scheme that uses the minimum number of PMs to place all the VMs, and ensures that the resource requirements of each VM are satisfied. We assume that the resource requirements of each VM will not exceed the resource capacity of one PM, and each VM is placed on only one PM, which means that VM cannot be further subdivided. VMs can share resources on the same PM without affecting each other. If one or more VMs are assigned to a PM, the PM needs to be turned on. In this paper, we consider the allocation of both CPU and memory resources. We assume that there are  $N$  PMs and  $N$  VMs. Let  $V = \{1, 2, \dots, N\}$  be a set of VMs and  $P = \{1, 2, \dots, N\}$  a set of PMs. The notation is summarized in Table I.

We formulate the allocation scheme as a 0-1 matrix whose element  $x_{ij}$  represents the assignment of physical machines. The

TABLE I. NOTATION OF THE VMP PROBLEM

Notation	Definition
$PM_i (1 \leq i \leq N)$	Physical machine $i$
$pc_i$	CPU of $PM_i$
$pm_i$	Memory of $PM_i$
$VM_j (1 \leq j \leq N)$	Virtual machine $j$
$vc_j$	CPU of $VM_j$
$vm_j$	Memory of $VM_j$
$x_{ij}$	Allocation matrix

row represents PM and the column represents VM. If  $VM_j$  is assigned to  $PM_i$ , then  $x_{ij} = 1$ , otherwise  $x_{ij} = 0$ , i.e.,

$$x_{ij} = \begin{cases} 1, & \text{if } VM_j \text{ is assigned to } PM_i \forall i \in P \text{ and } \forall j \in V. \\ 0, & \text{otherwise} \end{cases} \quad (6)$$

We need to ensure that every VM should be assigned, i.e.,

$$\sum_{i=1}^N x_{ij} = 1 \quad \forall j \in V. \quad (7)$$

The objective is to optimize the number of required PMs, which are calculated as follows:

$$\text{Minimize } f(s) = \sum_{i=1}^N y_i, \quad (8)$$

where

$$y_i = \begin{cases} 1, & \text{if } \sum_{j=1}^N x_{ij} \geq 1 \\ 0, & \text{otherwise} \end{cases} \quad \forall i \in P. \quad (9)$$

The resource allocation should also follow the following constraints

$$\sum_{j=1}^N vc_j \cdot x_{ij} \leq pc_i \cdot y_i \quad \forall i \in P, \quad (10)$$

$$\sum_{j=1}^N vm_j \cdot x_{ij} \leq pm_i \cdot y_i \quad \forall i \in P. \quad (11)$$

Studies have shown that the energy consumption of PM is linearly related to the CPU usage of PM [20]. However, an open but idle PM can also consume 50%-70% of the energy consumption in full load condition [21]. Therefore, the energy consumption model in this paper is as follows:

$$P(u) = k \cdot P_{\max} + (1-k) \cdot P_{\max} \cdot u, \quad (12)$$

where  $P_{\max}$  is the maximum energy consumption of a PM under full load conditions.  $k$  indicates the idle energy consumption ratio of an opened PM.  $u$  indicates the CPU usage of a PM.

### A. Encoding of SCLPSO

The VMP problem is a combinatorial optimization problem defined in discrete space. Therefore, the encoding scheme needs to meet the discretization requirement and the constraints of VMP. According to the S-PSO framework, the set-based encoding scheme in the proposed SCLPSO is defined as follows.

#### 1) Position

A position  $X$  represents a feasible assignment scheme. Each particle's position is an  $N$ -tuple  $X = (X_1, X_2, \dots, X_n)$  where  $n$  is the number of active PMs. Each element  $X_i$  in the  $N$ -tuple is a set which represents the VMs assigned on this PM. Different PMs may have different number of VMs on it. For example, a position  $X$  is given as  $X = (\{VM_{i1}, VM_{i2}\}, \{VM_{i3}, VM_{i4}, VM_{i5}\}, \{VM_{i6}\}, \dots)$ . It means that  $VM_{i1}, VM_{i2}$  are assigned on  $PM_1$ ,  $VM_{i3}, VM_{i4}, VM_{i5}$  are assigned on  $PM_2$ ,  $VM_{i6}$  is assigned on  $PM_3$ , and so on. If the element set  $X_i$  is empty, it means that no VM is assigned on the  $PM_i$ .

#### 2) Velocity

In S-PSO, velocity  $V$  is also an  $N$ -tuple  $V = (V_1, V_2, \dots, V_n)$ , where each element  $V_i$  is a set with probabilities. The probability determines the chance that the particle will learn from the element  $e$  to build a new position.

For example, the following velocity  $V$  is given

$V = (\{VM_{i1} / 0.5, VM_{i2} / 0.4\}, \{VM_{i3} / 0.7, VM_{i4} / 0.6\}, \{\}, \dots)$ . It means that  $VM_{i1}$  has the probability of 0.5 to be assigned to  $PM_1$ ,  $VM_{i2}$  has the probability of 0.4 to be assigned to  $PM_1$ ,  $VM_{i3}$  has the probability of 0.7 to be assigned to  $PM_2$ , and so forth.

For convenience, here we use  $V_i^j$  to describe the probability that  $VM_j$  will be assigned on  $PM_i$ .

### B. The Velocity Updating

Following the S-PSO framework defined in [16] and the velocity updating rule of CLPSO [17] given in (4), the proposed SCLPSO updates velocities of particles using the following operators:

#### 1) Coefficient $\times$ Velocity

The coefficient can be a constant or a random number which is a nonnegative real number. According to the S-PSO framework, the operator is defined as follows:

$$c \times V = \{e / p'(e) \mid e \in E\},$$

$$p'(e) = \begin{cases} 1, & \text{if } c \times p(e) > 1 \\ c \times p(e), & \text{otherwise} \end{cases}. \quad (13)$$

#### 2) Position – Position

In S-PSO framework, a position is given by a crisp set, and the minus operator between two crisp set is the difference set. Given two position sets  $A$  and  $B$ , the operator is defined as follows:

$$A - B = \{e \mid e \in A \text{ and } e \notin B\}. \quad (14)$$

It should be noticed that the minus operation is executed in each element set. For example, we assume that the number of VMs and PMs is 5. Given  $X = (\{1\}, \{2,3\}, \{4,5\}, \{\}, \{\})$  and  $GBest = (\{1\}, \{2,4\}, \{3,5\}, \{\}, \{\})$ , we then have  $GBest - X = (\{\}, \{4\}, \{3\}, \{\}, \{\})$ . In fact, the effect of  $PBest - X$  or  $GBest - X$  is to find out the elements used by better positions but not used by the current position. We figure out the difference set, and its elements are valuable to improve the current position. Just like the example,  $VM_4$  should be assigned on  $PM_2$ , and  $VM_3$  should be assigned on  $PM_3$ .

### 3) Coefficient $\times$ (Position - Position)

The result of "Position-Position" is also a crisp set. The multiplication operator between a coefficient and a crisp set is to generate a new velocity. The operation is defined as follows:

$$c \times E' = \{e \mid p'(e) \mid e \in E'\},$$

$$p'(e) = \begin{cases} 1, & \text{if } e \in E' \text{ and } c > 1 \\ c, & \text{if } e \in E' \text{ and } 0 \leq c \leq 1. \\ 0, & \text{if } e \notin E' \end{cases} \quad (15)$$

For example, suppose the coefficient  $c = 0.5$  and  $GBest - X = (\{\}, \{4\}, \{3\}, \{\}, \{\})$ , the  $c * (GBest - X)$  will be  $GBest - X = (\{\}, \{4/0.5\}, \{3/0.5\}, \{\}, \{\})$ . It implies that  $V_2^4 = 0.5$  and  $V_3^3 = 0.5$ .

### 4) Velocity + Velocity

Finally, we define the addition operator between two sets with possibilities.

$$V_1 + V_2 = \{e \mid \max(p_1(e), p_2(e)) \mid e \in E\}. \quad (16)$$

We choose the larger probability between two crisp sets to generate a new velocity.

## C. Heuristic Factor

In traditional allocation strategies, algorithms seldom take the relationship between VM and PM into account. However, if such relationship can be utilized, we can better guide the distribution. For example, when a VM is placed on a PM, the current resource utilization of the PM can be greatly improved. Then we can choose this assignment scheme in priority. In this paper, we introduce the heuristic factors  $\eta$  to increase the resource utilization of PM and balance the usage of different physical resources of PM at the same time.

The heuristic factor adopts the greedy strategy to improve the assignment schemes. In order to reduce the number of final PMs, each PM needs to host as many VMs as possible, which can increase the utilization rate of PM resources. Balancing the use of various physical resources can avoid the situation that some resources are fully used while other resources are at idle. Based on this, heuristic factor is designed to increase the utilization of different resources and balance the use of different resources on the same PM, resulting in a higher and similar utilization of different resources.

The heuristic factor is related to VMs and PMs. It is calculated by the resource utilization that can be brought to the

PM after the VM is assigned to the PM. The heuristic factor with a smaller value indicates that the VM is more suitable for placing on this PM. The heuristic factor in this paper is defined as follows:

$$\eta(i, j) = \frac{\left| \frac{pc_i - uc_i - vc_j}{pc_i} - \frac{pm_i - um_i - vm_j}{pm_i} \right|}{\left| \frac{pc_i - uc_i - vc_j}{pc_i} \right| + \left| \frac{pm_i - um_i - vm_j}{pm_i} \right|}. \quad (17)$$

In (17),  $pc$  is the CPU capacity of  $PM_i$ ,  $uc$  is the CPU usage,  $pm$  and  $um$  is the information of memory.  $vc$  and  $vm$  are the CPU requirements and memory requirements for  $VM_j$ . The denominator of (17) measures the utilization in both CPU and memory resources. The numerator of (17) considers the remaining resources on the physical machine. If  $VM_j$  could increase the resource utilization of  $PM_i$  as well as balance the usage of different physical resources of  $PM_i$ ,  $\eta$  will be smaller. This selection strategy will reduce the number of active PMs, which can further improve the quality of solutions.

## D. Position Updating with the Step-by-Step Strategy

We can use the (4) and the operators defined on crisp sets to update velocities. When generating new positions, we use the step-by-step strategy, which considers each VM and generates the new position by placing VMs one by one.

Each VM has its own velocity subset, which represents the probabilities to be placed on every PM. Firstly, a random number  $\alpha \in (0, 1)$  is generated in each iteration, and then a cut set is generated according to (18).

$$cut_\alpha(V_i^j) = \{e \mid e \mid p(e) \in V_i^j \text{ and } p(e) \geq \alpha\}. \quad (18)$$

For each element in the cut set, (17) is used to calculate the heuristic factor between the current VM and the PM to find the most suitable assignment. The candidate PMs are sorted in ascending order according to the heuristic factor, and then the PM with smaller heuristic factor is selected. If a suitable PM can be found successfully during this process, the allocation of the VM is completed. If not, the VM is added to a reassignment set. This process is repeated for each VM until all VMs have been considered.

During reassignment, the elements in the reassignment set represent unsuccessfully allocated VMs, and then we use (17) to calculate the heuristic factors between it and the PMs that have been turned on. Then sort all the heuristic factors and select the PM with smallest heuristic factor. If there is a suitable PM, allocate and complete the allocation of this VM. If we cannot find a suitable PM, then turn on a new PM to place this VM. Repeat this process until the reassignment set is empty. The above is the process of building a solution step by step. When this process finishes, we can obtain a new feasible solution.

## E. Complete SCLPSO Algorithm

The complete flowchart of SCLPSO is shown in Fig. 1. Firstly, we initialize the population and each VM is placed on a

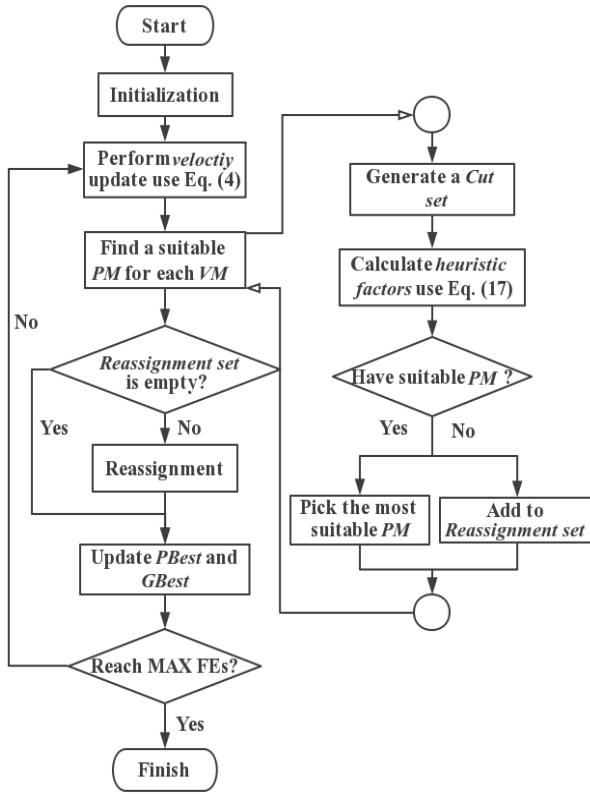


Fig. 1. Flowchart of the SCLPSO algorithm.

PM, which means  $X = \{\{1\}, \{2\}, \dots, \{N\}\}$ . The number of available PMs is equal to the number of VMs. Each element in the velocity set is assigned a random value in  $[0, 1]$ .

SCLPSO uses the updating rule of CLPSO in (4) and S-PSO to update velocities. Then we enter the process of solution construction. For each VM, we will generate a cut set using (18). And we will calculate the heuristic factors  $\eta$  for every PM in cut set and current VM using (17). If we can find the most suitable

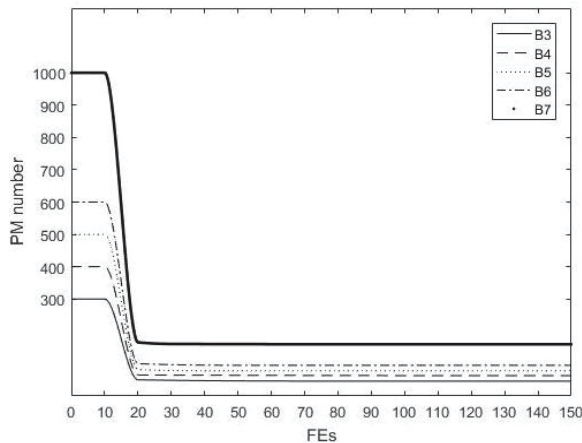


Fig. 2. The convergence curves of SCLPSO on instances B3-B7.

PM according to  $\eta$ , then we finish this VM assignment. Otherwise, we add it to the reassignment set. We will do this process for all VMs.

Then we check the reassignment set. If there still exist unassigned VMs, we go into the reassignment process and find suitable PMs to hold the VMs until the set is empty. Finally, we update the  $PBest$  and  $GBest$ .

We will repeat this process until the algorithm reaches the maximum number of fitness evaluations.

## V. EXPERIMENTS AND COMPARISONS

We conduct experiments to test and verify the effectiveness of SCLPSO. All compared algorithms are implemented in C++ and the operating environment is CPU i7 and 4.0 GB RAM.

The experiment will use the standard test set given in [26] (i.e., Test A) and we design two other scenarios, Test B and Test C, to test the resource bottlenecks and the heterogeneity of physical machines. We compare SCLPSO algorithm with Ant Colony Optimization (ACO) based algorithm [27], [28] multi-objective algorithm (MACO) [29], HACOPSO [30] algorithm, and FFD [13] heuristic method. The ACO algorithm is suitable for solving discrete problems, [28] is based on max-min ant colony algorithm to solve the problem. [29] proposed multi-objective algorithm MACO and has certain advantages for solving multi-resource optimization in VMP problems. [30] proposed HACOPSO which combines ACO and PSO together. Its experimental results have shown superiority to most existing algorithms. The FFD sorts the VMs in descending order, first considering the CPU factor, and then considering the memory factor to be allocated on the first suitable PM. The FFD algorithm obtains better results than other deterministic algorithms [13]. Therefore, FFD is considered as a representative heuristic deterministic algorithm.

In the experiments, we set the number of populations  $POPSIZE$  to 10, and  $MAX\_FES$  is the maximum number of iterations, which set to 150. Parameter  $c_1$  and  $c_2$  are both 2.0. As for  $\omega$ , we use the linear decrement strategy in (19),

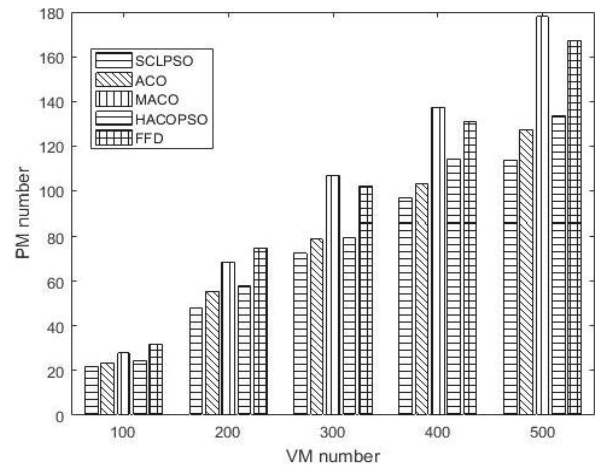


Fig. 3. The histogram of Test C.

TABLE II. EXPERIMENTAL RESULT COMPARISONS IN TEST A

Instance	No. VM	optimum	SCLPSO	ACO	MACO	HACOPSO	FFD
A1	1363	112	<b>115.00</b>	116.50	130.26	117.56	133.00
A2	2314	191	<b>196.00</b>	199.03	222.16	204.03	229.00
A3	2639	216	<b>221.00</b>	225.33	251.13	238.93	258.00
A4	2972	241	<b>247.00</b>	251.43	282.00	263.93	288.00
A5	3289	267	<b>274.00</b>	278.76	312.26	322.83	320.00

TABLE III. EXPERIMENTAL RESULT COMPARISONS IN TEST B

Instance	No. VM	SCLPSO	SCLPSO (without $\eta$ )	ACO	MACO	HACOPSO	FFD
B1	100	<b>16.00</b>	<b>16.00</b>	<b>16.00</b>	<b>16.00</b>	17.00	18.00
B2	200	<b>32.00</b>	32.40	33.10	33.10	34.30	37.00
B3	300	<b>46.00</b>	46.70	46.73	47.20	47.10	53.00
B4	400	<b>63.40</b>	64.50	64.54	66.00	65.33	74.00
B5	500	<b>78.00</b>	80.86	79.10	82.23	81.50	92.00
B6	600	<b>94.80</b>	96.03	97.10	99.16	100.20	111.00
B7	1000	<b>160.00</b>	162.10	162.86	169.86	175.66	184.00

TABLE IV. EXPERIMENTAL RESULT COMPARISONS IN TEST C

Instance	No. VM	SCLPSO	ACO	MACO	HACOPSO	FFD
C1	100	<b>21.63</b>	23.33	28.35	24.56	32
C2	200	<b>48.10</b>	55.56	68.26	57.85	75
C3	300	<b>72.90</b>	79.44	106.90	79.40	102
C4	400	<b>96.86</b>	103.56	137.20	115.50	131
C5	500	<b>113.46</b>	127.56	178.50	134.60	167

$$\omega = \omega_{\max} - \frac{(\omega_{\max} - \omega_{\min})}{\text{MAX\_FES}} * T, \quad (19)$$

where  $\omega_{\max}$  is 0.9,  $\omega_{\min}$  is 0.4, and  $T$  is the current generation. The parameters of RGGA, ACO, MACO and HACOPSO are set according to their authors' recommendation. Each test runs 30 times and we compare the average results.

#### A. Test A: Large-Scale Homogeneous Test

The experimental data comes from [26] and the test scale is from 1000 to 3000. Each PM has 500 CPUs and 500 GB of RAM. The CPU demand for the VM is between [1,128] and the memory requirement is between [0,100]. The CPU and memory demand ratio are close to 1:1. The experimental results are shown in Table II.

From the experimental results, we can see that SCLPSO performs better than the other algorithms. The result of the solution is closer to the theoretical optimal solution. Even in the case of increasing data size, the good performance can be maintained. This is due to the use of comprehensive learning strategy to update the velocity. It can make particles have more exemplars to learn and avoid the premature. The rest of the algorithms are slightly inadequate, and the quality of solutions decreases as the data scale increases, the distance between the optimal solution and the theoretical solution continues to widen. FFD has a poor performance on large-scale solutions. With the

expansion of scale, the performance of other algorithms continues to decline, and the efficiency of resource utilization for physical machines continues to decline as well.

#### B. Test B: Bottleneck Resource Test

In order to better test the performance of SCLPSO, we designed a bottleneck resource test. In this experiment, the data size ranged from 100 to 1000. We specify that each PM has 16 CPUs and 32 GB of RAM. The CPU requirement for each VM is between [1,4], the memory requirement is between [1,8], and the VM requirements follow a uniform distribution. The ratio of CPU demand to memory demand in the experiment is close to 1:2 with an obvious resource bottleneck. The results of this experiment are shown in Table III.

The data of this experiment is a resource bottleneck. SCLPSO has better performance than other compared algorithms. When the demand of VM is small, all algorithms can obtain good solutions. However, with the expansion of VM demand, how to properly deal with the bottleneck of virtual machine resources has become a major problem, and the quality of solutions from other algorithms has declined. To demonstrate the function of the heuristic factor, we design a SCLPSO version without heuristic factor and select PM randomly. As the demand increases, the gap with complete SCLPSO becomes more pronounced.

From the convergence curves in Fig. 2, we find that SCLPSO can converge to a high-quality at early iterations and have a slight improvement at later iterations. Combined with the heuristic factor, the step-by-step solution construction can find suitable PM for each VM and well use physical resources. This will increase the utilization of PMs and obtain high-quality solutions in a few iterations.

SCLPSO uses the heuristic factor  $\eta$  and cut sets to build a solution step by step, and dynamically calculates the relationship between the current VM and the available PMs. In constructing new solutions, SCLPSO tries to find the most suitable physical machine and balance the resource utilization of physical machines at the same time. This strategy can help converge to a high-quality solution in a few calculations.

### C. Test C: Heterogeneous Test

Both of the above experiments are tested on the same PMs. In this experiment, we considered heterogeneous PMs, that is, PMs have different physical resources. The data size ranges from 100-500. 10% PMs are configured with 32 CPUs and 128 GB of memory, and 90% PMs are configured with 16 CPUs and 32 GB of memory. The CPU demand for VMs is in [1,8] and the memory requirement is in [1,32], which follows a uniform distribution. The experimental results are presented in Table IV.

From the histogram in Fig. 3, we can find that SCLPSO has a great advantage in solving heterogeneous physical machines. With the expansion of the data scale, the advantages become more obvious. This is because SCLPSO considers the relationship between the current VM and the PMs that can be placed when arranging each VM, including CPU and memory, so it can arrange virtual machines relatively well. Compared to FFD, sorting and prioritizing one dimension can easily lead to a situation where the utilization of one resource is high while the other resources are low.

The experimental results show that SCLPSO algorithm performs better than the other comparison algorithms for large-scale VM demand, resource bottleneck or server heterogeneity. S-PSO framework and comprehensive learning strategy can handle large-scale problems well. With the devised heuristic factor and cut set, the solution is constructed step by step. The relationship between current VM and available PMs can be dynamically calculated to ensure each VM is reasonably arranged on the appropriate PM.

## VI. CONCLUSION

In this paper, based on the S-PSO framework and comprehensive learning strategy, we propose SCLPSO to solve the VMP problem which extends the original PSO to discrete searching space. The experimental results show that SCLPSO algorithm can solve large-scale optimization problems well, and it can also have better results on resource bottlenecks and heterogeneous situations. In future researches, we will try to apply SCLPSO in solving other discrete combinatorial problems, such as cloud workflow scheduling and insurance investment planning [31].

This work was supported in part by the National Natural Science Foundation of China under Grant 61622206 and Grant 61332002, the Natural Science Foundation of Guangdong under Grant 2015A030306024, and the Open Project Program of the State Key Laboratory of Mathematical Engineering and Advanced Computing (Corresponding Author: Wei-Neng Chen).

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